

## MATH 3311, FALL 2025: LECTURE 31, NOVEMBER 12

Video: <https://youtu.be/q05B0v3q2cA>

### Finitely generated abelian groups

**Definition 1.** Suppose that  $G$  is a group and  $X \subset G$  is a subset. The **subgroup generated by  $X$** , denoted  $\langle X \rangle \leq G$  is the smallest subgroup of  $G$  containing  $X$ .

*Remark 1.* This notion makes sense, since the intersection of any collection of subgroups containing  $X$  is once again a subgroup containing  $X$ , so  $\langle X \rangle$  can be taken to be the intersection of all subgroups containing  $X$ .

*Remark 2.* More concretely, we have

$$\langle X \rangle = \{x_1^{\pm 1} x_2^{\pm 2} \cdots x_m^{\pm 1} : x_i \in X, m \geq 1\}.$$

That is, we take all possible products of elements of  $X$  as well as of their inverses.

*Remark 3.* If  $X = \{x\}$  is a singleton, then  $\langle X \rangle = \langle x \rangle$  is just the cyclic subgroup generated by the element  $x$ .

**Definition 2.**  $G$  is **finitely generated** if there is a finite subset  $X \subset G$  such that  $\langle X \rangle = G$ . In other words, there is a finite set of symbols such that every element of  $G$  can be expressed as a product of such symbols.

We will be concerned with the problem of *classifying* finitely generated abelian groups. That is, we want a complete, non-redundant list of such groups up to isomorphism. But before we enter the abelian realm, let us look at the following non-abelian example.

*Example 1.* Take

$$\mathrm{SL}_2(\mathbb{Z}) = \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} : a, b, c, d \in \mathbb{Z}, ad - bc = 1 \right\}$$

This is actually a *group* under matrix multiplication: The condition on the determinant tells us that we can write the inverse as

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} = \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$

Elements of  $\mathrm{SL}_2(\mathbb{Z})$  can be obtained as follows. Note that the condition  $ad - bc = 1$  shows that the pairs  $a, b, a, c, c, d$  and  $b, d$  are all relatively prime. In other words, the entries of each row and column of the matrix have to be relatively prime to each other.

Conversely, if  $a, b$  are relatively prime, then by Bezout we can find  $c, d$  such that  $ad - bc = 1$  (why?), and so we can find a matrix in  $\mathrm{SL}_2(\mathbb{Z})$  with the first row given by  $(a, b)$ . For example, we have

$$\begin{pmatrix} 2 & 3 \\ -1 & -1 \end{pmatrix} \in \mathrm{SL}_2(\mathbb{Z}).$$

In particular,  $\mathrm{SL}_2(\mathbb{Z})$  is an *infinite* group.

In any case, two matrices we can find in here are

$$T = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} ; S = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

Note that we have  $T^m = \begin{pmatrix} 1 & m \\ 0 & 1 \end{pmatrix}$  for any  $m \in \mathbb{Z}$  and we have  $S^2 = -I_2$  is the negative identity matrix. So  $T$  does not have finite order while  $S$  has order 4.

A non-trivial result now is that  $\mathrm{SL}_2(\mathbb{Z}) = \langle \{S, T\} \rangle$ : So this is a *non-abelian, finitely generated infinite* group.

Let us now move firmly into the abelian world. The starting point for our classification is the following observation.

**Definition 3.** For  $1 \leq i \leq m$ , the  $i$ -th **standard basis vector**  $\vec{e}_i \in \mathbb{Z}^m$  is the element with 1 as its  $i$ -th coordinate and 0s everywhere else. For example, in  $\mathbb{Z}^3$ , we have

$$\vec{e}_1 = (1, 0, 0), \vec{e}_2 = (0, 1, 0), \vec{e}_3 = (0, 0, 1).$$

*Remark 4.* The element  $(a_1, \dots, a_m) \in \mathbb{Z}^m$  can be written (uniquely) as a linear combination  $\sum_{i=1}^m a_i \vec{e}_i$ .

**Observation 1.** Suppose that  $G$  is an abelian group and  $X = \{x_1, \dots, x_m\} \subset G$  is a finite subset of elements. Then there is a unique homomorphism

$$f : \mathbb{Z}^m \rightarrow G$$

such that  $f(\vec{e}_i) = x_i$  for  $i = 1, \dots, m$ .

*Proof.* The point is that, because of the homomorphism property, given this description for standard basis vectors, we must have

$$f((a_1, \dots, a_m)) = f\left(\sum_{i=1}^m a_i \vec{e}_i\right) = f(a_1 \vec{e}_1 + \dots + a_m \vec{e}_m) = f(a_1 \vec{e}_1) f(a_2 \vec{e}_2) \dots f(a_m \vec{e}_m) = x_1^{a_1} \dots x_m^{a_m}.$$

Here, in the third and fourth equalities, we have used the homomorphism property of  $f$ : Note that  $f(a_i \vec{e}_i) = f(\vec{e}_i)^{a_i}$ , because we are using multiplicative notation for the operation in  $G$ .

So the only possibility for  $f$  as a function is  $f((a_1, \dots, a_m)) = x_1^{a_1} \dots x_m^{a_m}$ . We need to know that this is a *homomorphism*. For this, note:

$$\begin{aligned} f((a_1, \dots, a_m)) \cdot f((b_1, \dots, b_m)) &= (x_1^{a_1} \dots x_m^{a_m})(x_1^{b_1} \dots x_m^{b_m}) \\ &= x_1^{a_1+b_1} \dots x_m^{a_m+b_m} \\ &= f((a_1 + b_1, \dots, a_m + b_m)) \\ &= f((a_1, \dots, a_m) + (b_1, \dots, b_m)). \end{aligned}$$

Here, in the second line, we have used the *abelianness* of  $G$  to collect all the powers of each  $x_i$  together.  $\square$

*Remark 5.* We didn't actually use the full strength of abelianness of  $G$ . You just needed the elements  $x_1, \dots, x_m$  to commute with each other. So we can say that there is a canonical *bijection*

$$\text{Hom}(\mathbb{Z}^m, G) \xrightarrow[\simeq]{f \mapsto (f(\vec{e}_1), \dots, f(\vec{e}_m))} \{m\text{-tuples of commuting elements in } G\}.$$

**Observation 2.** If  $f$  is as in Observation 1, then we have

$$\text{im } f = \langle X \rangle \leq G.$$

*Proof.* This follows from the description of  $f$  in the proof of Observation 1, combined with Remark 2.  $\square$

**Observation 3.** If  $f$  is as in Observation 1, then  $f$  is surjective if and only if  $\langle X \rangle = G$ .

Putting this all together, we get:

**Proposition 1.** Suppose that  $G$  is an abelian group. Then the following are equivalent:

- (1)  $G$  is finitely generated.
- (2) There exists  $m \geq 1$  and a surjective homomorphism  $f : \mathbb{Z}^m \rightarrow G$ .
- (3) There exists  $m \geq 1$  and a subgroup  $H \trianglelefteq \mathbb{Z}^m$  such that we have an isomorphism

$$\mathbb{Z}^m / H \xrightarrow{\cong} G.$$

*Proof.* Observations 1-3 tell us that (1)  $\Leftrightarrow$  (2), and the equivalence (2)  $\Leftrightarrow$  (3) is just the first isomorphism theorem.  $\square$